Geometry



## Determine the position on the image of the camera center



## Crop and pad to make symmetric

1920 pixels 262 pixels 1431 1431 1636 pixels 1636 pixels

New FOV of padded symmetric view is 2\*70.14 = 140.28 deg

```
vfov = 2 atan[ height tan(hfov/2) / width]
```

## SO

vfov should be 2 atan(1636 tan(140.28/2) / 2862) = 115 degrees

Note this is different to the quoted value

Pipeline



Left

Right







Pad to symmetric frustum





Map to half equirectangular including yaw rotation.



